

**Product Manual** 

# Barracuda® 7200.9 PATA

ST3500841A	ST3200827A
ST3500641A	ST3160812A
ST3400833A	ST3160212A
ST3400633A	ST3120814A
ST3320833A	ST3120213A
ST3320633A	ST3802110A
ST3300822A	ST3402111A
ST3300622A	
ST3250824A	

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ST3250624A

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One gigabyte, or GB, equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting. Quantitative usage examples for various applications are for illustrative purposes. Actual quantities will vary based on various factors, including file size, file format, features and application software. Seagate reserves the right to change, without notice, product offerings or specifications.

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## 1.0 Introduction

This manual describes the functional, mechanical and interface specifications for the following Seagate® Barracuda® 7200.9 PATA model drives:

ST3500841A	ST3300822A	ST3160212A
ST3500641A	ST3300622A	ST3120814A
ST3400833A	ST3250824A	ST3120213A
ST3400633A	ST3250624A	ST3802110A
ST3320833A	ST3200827A	ST3402111A
ST3320633A	ST3160812A	01040211174

These drives provide the following key features:

- 7,200-RPM spindle speed
- High instantaneous (burst) data transfer rates (up to 100 Mbytes per second) using Ultra DMA mode 5.
- Tunneling Magnetoresistive (TMR) recording heads provide the drives with increased areal density.
- State-of-the-art cache and on-the-fly error-correction algorithms.
- Full-track multiple-sector transfer capability without local processor intervention.
- Quiet operation.
- 350 Gs nonoperating shock.
- SeaTools diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Support for Read Multiple and Write Multiple commands.
- Support for autodetection of master/slave drives that use cable select (CSEL).

## 2.0 Drive specifications

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate the following drive models:

ST3500841A	ST3300822A	ST3160212A
ST3500641A	ST3300622A	ST3120814A
ST3400833A	ST3250824A	ST3120213A
ST3400633A	ST3250624A	ST3802110A
ST3320833A	ST3200827A	ST3402111A
ST3320633A	ST3160812A	

## 2.1 Specification summary table

The specifications listed in the table below are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

Table 1: Drive specifications summary for 500 Gbyte models

Drive specification	ST3500841A	ST3500641A	
Formatted Gbytes (512 bytes/sector)*	500		
Guaranteed sectors	976,773,168		
Bytes per sector	512	512	
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	815.2		
Sustained data transfer rate OD (Mbytes/sec max)	65.0		
I/O data-transfer rate (Mbytes/sec max)	100		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes Ultra DMA modes 0–5	0–2	
Cache buffer	8 Mbytes	16 Mbytes	
Height (mm max)	26.1 mm (1.028 inches	s)	
Width (mm max)	101.6 mm (4.000 inche	es) +/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inch	nes)	
Weight (max)	710 grams (1.57 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	13.0 sec	13.0 sec	
Standby to ready (sec max)	13.0 sec	13.0 sec	
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write	<0.8 (read), <1.0 (write)	
Average seek, read (msec typical)	<11.0		
Average seek, write (msec typical)	<12.0		
Startup current (typical) 12V (peak)	2.9 amps	2.9 amps	
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoper	ating)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperat	ing)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)	
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (max at 2 msec)	63 Gs		
Non-Operational Shock (max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Lim 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	ited displacement	

Drive specification	ST3500841A	ST3500641A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limite 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs		
Drive acoustics, sound power (bels)			
Idle**	2.8 (typical) 3.0 (max)		
Quiet seek	3.2 (typical) 3.4 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	0.34%	
Warranty	To determine the warran to access the following v www.seagate.com/suppr From this page, click on asked to provide the driv number) and country of	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		

Table 2: Drive specifications summary for 400 Gbyte models

Drive specification	ST3400633A	ST3400833A	
Formatted Gbytes (512 bytes/sector)*	400		
Guaranteed sectors	781,422,768		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.69		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	815.2		
Sustained data transfer rate OD (Mbytes/sec max)	65.0		
I/O data-transfer rate (Mbytes/sec max)	100		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0– Ultra DMA modes 0–5	2	
Cache buffer	16 Mbytes	8 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	<u> </u>	
Width (mm max)	101.6 mm (4.000 inches) -	+/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)	)	
Weight (max)	710 grams (1.57 lb.)	· · · · · · · · · · · · · · · · · · ·	
Average latency (msec)	4.16		
Power-on to ready (sec max)	13.0 sec	13.0 sec	
Standby to ready (sec max)	13.0 sec	13.0 sec	
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0		
Average seek, write (msec typical)	<12.0		
Startup current (typical) 12V (peak)	2.9 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperatin	0° to 60°C (operating) -40° to 70°C (nonoperating)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)	5% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	l displacement	

Drive specification	ST3400633A	ST3400833A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited dis 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs		
Drive acoustics, sound power (bels)			
Idle**	2.8 (typical) 3.0 (max)		
Quiet seek	3.2 (typical) 3.4 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	0.34%	
Warranty	to access the following web p www.seagate.com/support/se From this page, click on the "\" be asked to provide the drive part number) and country of p	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		

Table 3: Drive specifications summary for 320 Gbyte models

Drive specification	ST3320633A	ST3320633A	
Formatted Gbytes (512 bytes/sector)*	320		
Guaranteed sectors	625,142,448		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.69		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	76.6		
I/O data-transfer rate (Mbytes/sec max)	100		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–5	!	
Cache buffer	16 Mbytes	8 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches) +	/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	655 grams (1.44 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	11.0 sec		
Standby to ready (sec max)	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0		
Average seek, write (msec typical)	<12.0		
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating	<b>3</b> )	
Temperature gradient (°C per hour max)	30°C (nonoperating)	20°C (operating) 30°C (nonoperating)	
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited ( 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	displacement	

Drive specification	ST3320633A ST	3320633A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited displacemer 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs		
Drive acoustics, sound power (bels)			
ldle**	2.7 (typical) 2.9 (max)		
Quiet seek	3.0 (typical) 3.2 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%		
Warranty	to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify You be asked to provide the drive serial nur part number) and country of purchase.	To determine the warranty for a specific drive, use a web browser to access the following web page:	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		

Table 4: Drive specifications summary for 300 Gbyte models

Drive specification	ST3300622A	ST3300822A	
Formatted Gbytes (512 bytes/sector)*	300		
Guaranteed sectors	586,072,368		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.69		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	76.6		
I/O data-transfer rate (Mbytes/sec max)	100		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–5 Ultra DMA modes 0–5	2	
Cache buffer	16 Mbytes	8 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	<u> </u>	
Width (mm max)	101.6 mm (4.000 inches) -	+/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	655 grams (1.44 lb.)	,	
Average latency (msec)	4.16		
Power-on to ready (sec max)	11.0 sec		
Standby to ready (sec max)	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0		
Average seek, write (msec typical)	<12.0		
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperatin	g)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)	5% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)	· · · · · · · · · · · · · · · · · · ·	
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	displacement	

Drive specification	ST3300622A ST3300822A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited displacement 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs	
Drive acoustics, sound power (bels)		
ldle**	2.7 (typical) 2.9 (max)	
Quiet seek	3.0 (typical) 3.2 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	
Warranty	5 years on distribution units. To determine the warranty for a specific drive, use a web brow to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You w be asked to provide the drive serial number, model number (o part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	

Table 5: Drive specifications summary for 250 and 200 Gbyte models

Drive specification	ST3250624A	ST3250824A	ST3200827A	
Formatted Gbytes (512 bytes/sector)*	250		200	
Guaranteed sectors	488,397,168 390,721,9		390,721,968	
Bytes per sector	512			
Default sectors per track	63			
Default read/write heads	16			
Default cylinders	16,383			
Recording density, KBPI (kbits/in max)	790.1			
Track density, KTPI (ktracks/in avg.)	124.5			
Areal density, (Gbits/in <sup>2</sup> avg)	97.69			
Spindle speed (RPM)	7,200			
Internal data transfer rate (Mbits/sec max)	867.2			
Sustained data transfer rate OD (Mbytes/sec max)	76.6			
I/O data-transfer rate (Mbytes/sec max)	100			
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA mo Ultra DMA modes (			
Cache buffer	16 Mbytes	8 Mbytes		
Height (mm max)	26.1 mm (1.028 inc	hes)		
Width (mm max)	101.6 mm (4.000 in	ches) +/- 0.010 inches		
Length (mm max)	146.99 mm (5.787	inches)		
Weight (max)	580 grams (1.28 lb.	)		
Average latency (msec)	4.16			
Power-on to ready (sec max)	11.0 sec			
Standby to ready (sec max)	11.0 sec	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (v	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0			
Average seek, write (msec typical)	<12.0			
Startup current (typical) 12V (peak)	2.8 amps			
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%			
Ambient temperature	–40° to 70°C (nono	0° to 60°C (operating) -40° to 70°C (nonoperating)		
Temperature gradient (°C per hour max)	30°C (nonoperating	20°C (operating) 30°C (nonoperating)		
Relative humidity		5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max			
Wet bulb temperature (°C max)	` ` .	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating		-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)		-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs			
Vibration, operating	5–22 Hz: 0.25 Gs, 1 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 (	Limited displacement		

Drive specification	ST3250624A ST3250824A ST3200827A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited displacement 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs	
Drive acoustics, sound power (bels)		
Idle**	2.7 (typical) 2.9 (max)	
Quiet seek	3.0 (typical) 3.2 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	
Warranty	5 years on distribution units. To determine the warranty for a specific drive, use a web browse to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	

Table 6: Drive specifications summary for 160 Gbyte models

Drive specification	ST3160812A	ST3160212A	
Formatted Gbytes (512 bytes/sector)*	160		
Guaranteed sectors	312,581,808		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	840.0		
Track density, KTPI (ktracks/in avg.)	141.5		
Areal density, (Gbits/in <sup>2</sup> avg)	119.0		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	83.0		
I/O data-transfer rate (Mbytes/sec max)	100		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0- Ultra DMA modes 0–5	-2	
Cache buffer	8 Mbytes	2 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches)	+/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches	5)	
Weight (max)	580 grams (1.28 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	<10.0 sec	<10.0 sec	
Standby to ready (sec max)	<10.0 sec	<10.0 sec	
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0	<11.0	
Average seek, write (msec typical)	<12.0	<12.0	
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperati	ng)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating	g)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limite 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	d displacement	

Drive specification	ST3160812A	ST3160212A
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs	displacement
Drive acoustics, sound power (bels)		
Idle**	2.5 (typical) 2.7 (max)	
Quiet seek	2.8 (typical) 3.0 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	
Warranty	5 years on distribution units. To determine the warranty for a specific drive, use a web browse access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will asked to provide the drive serial number, model number (or parnumber) and country of purchase. The system will display the wranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	

Table 7: Drive specifications summary for 120 Gbyte models

Drive specification	ST3120814A ST3120213A	
Formatted Gbytes (512 bytes/sector)*	120	
Guaranteed sectors	234,441,648	
Bytes per sector	512	
Default sectors per track	63	
Default read/write heads	16	
Default cylinders	16,383	
Recording density, KBPI (kbits/in max)	840.0	
Track density, KTPI (ktracks/in avg.)	141.5	
Areal density, (Gbits/in <sup>2</sup> avg)	119.0	
Spindle speed (RPM)	7,200	
Internal data transfer rate (Mbits/sec max)	867.2	
Sustained data transfer rate OD (Mbytes/sec max)	83.0	
I/O data-transfer rate (Mbytes/sec max)	100	
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–5	
Cache buffer	8 Mbytes 2 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	
Width (mm max)	101.6 mm (4.000 inches) +/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)	
Weight (max)	580 grams (1.28 lb.)	
Average latency (msec)	4.16	
Power-on to ready (sec max)	<10.0 sec	
Standby to ready (sec max)	<10.0 sec	
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)	
Average seek, read (msec typical)	<11.0	
Average seek, write (msec typical)	<12.0	
Startup current (typical) 12V (peak)	2.8 amps	
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%	
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)	
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max	
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)	
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)	
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)	
Operational Shock (Gs max at 2 msec)	63	
Non-Operational Shock (Gs max at 2 msec)	350 Gs	
Vibration, operating	5–22 Hz: 0.25 Gs, Limited displacement 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	

Drive specification	ST3120814A	ST3120213A
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limi 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs	ited displacement
Drive acoustics, sound power (bels)		
Idle**	2.5 (typical) 2.7 (max)	
Quiet seek	2.8 (typical) 3.0 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	
Warranty  5 years on distribution units. To determine the warranty for a specific driv browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Wa will be asked to provide the drive serial numb (or part number) and country of purchase. T play the warranty information for your drive.		anty for a specific drive, use a web following web page: port/service/ n the "Verify Your Warranty" link. You the drive serial number, model number ountry of purchase. The system will dis-
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	

Table 8: Drive specifications summary for 80 and 40 Gbyte models

Drive specification	ST3802110A	ST3402111A	
Formatted Gbytes (512 bytes/sector)*	80	40	
Guaranteed sectors	156,301,488	78,165,360	
Bytes per sector	512	·	
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	840.0	611.5	
Track density, KTPI (ktracks/in avg.)	141.5	103.9	
Areal density, (Gbits/in <sup>2</sup> avg)	119.0	63.53	
Spindle speed (RPM)	7,200	<u> </u>	
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	83.0	69.4	
I/O data-transfer rate (Mbytes/sec max)	100	<u> </u>	
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0 Ultra DMA modes 0–5	-2	
Cache buffer	2 Mbytes		
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches)	) +/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches	s)	
Weight (max)	580 grams (1.28 lb.)	525 grams (1.16 lb.)	
Average latency (msec)	4.16	<u>'</u>	
Power-on to ready (sec max)	<10.0 sec		
Standby to ready (sec max)	<10.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<11.0	<11.0	
Average seek, write (msec typical)	<12.0	<12.0	
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	` '	0° to 60°C (operating) -40° to 70°C (nonoperating)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 95% (nonoperating	5% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limite 22–350 Hz: 0.5 Gs 350–500 Hz: 0.25 Gs	d displacement	

Drive specification	ST3802110A	ST3402111A	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited ( 22–350 Hz: 5.0 Gs 350–500 Hz: 1.0 Gs	displacement	
Drive acoustics, sound power (bels)			
Idle**	2.5 (typical) 2.7 (max)	2.0 (typical) 2.3 (max)	
Quiet seek	2.7 (typical) 2.9 (max)	2.4 (typical) 2.6 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%		
Warranty	To determine the warranty fraccess the following web powers. When we want to be accessed to provide the drive something to be asked to provide the drive something and country of pure something the warranty of pure something the warranty of the access to be accessed to provide the drive something the warranty of the warranty of the access the access to be accessed to be accessed to the access to be accessed to the access to be accessed to the access to the access the access the following web provides the access the access the access the access the access the following web provides the access to access the ac	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.2 Formatted capacity

Model	Formatted capacity*	Guaranteed sectors	Bytes per sector
ST3500841A	500 Gbytes	976,773,168	512
ST3500641A	500 Gbytes	976,773,168	512
ST3400833A	400 Gbytes	781,422,768	512
ST3400633A	400 Gbytes	781,422,768	512
ST3320833A	320 Gbytes	625,142,448	512
ST3320633A	320 Gbytes	625,142,448	512
ST3300822A	300 Gbytes	586,072,368	512
ST3300622A	300 Gbytes	586,072,368	512
ST3250824A	250 Gbytes	488,397,168	512
ST3250624A	250 Gbytes	488,397,168	512
ST3200827A	200 Gbytes	390,721,968	512
ST3160812A	160 Gbytes	312,581,808	512
ST3160212A	160 Gbytes	312,581,808	512
ST3120814A	120 Gbytes	234,441,648	512
ST3120213A	120 Gbytes	234,441,648	512
ST3802110A	80 Gbytes	156,301,488	512
ST3402111A	40 Gbytes	78,165,360	512

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

### 2.2.1 LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to n-1, where n is the number of guaranteed sectors as defined above.

See Section 4.1.2, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137 Gbytes.

## 2.3 Default logical geometry

Cylinders	Read/write heads	Sectors per track
16,383	16	63

## 2.4 Recording and interface technology

Interface	ATA
Recording method	16/17 EPRML
Recording density KBPI (kbits/inch max)	790.1 (500, 400, 320, 300, 250 and 200GB models) 840.0 (160, 120 and 80GB models) 611.5 (40GB model)
Track density KTPI (ktracks/inch avg)	124.5 (500, 400, 320, 300, 250 and 200GB models) 141.5 (160, 120 and 80GB models) 103.9 (40GB model)
Areal density (Gbits/inch <sup>2</sup> avg)	97.69 (500, 400, 320, 300, 250 and 200GB models) 119.0 (160, 120 and 80GB models) 63.53 (40GB model)
Spindle speed (RPM) (± 0.2%)	7,200
Internal data-transfer rate (Mbits/sec max)	815.2 (400 and 500GB models) 867.2 (all other models)
Sustained data transfer rate OD (Mbytes/sec max)	65.0 (400 and 500GB models) 76.6 (320, 300, 250 and 200GB models) 83.0 (160, 120 and 80GB models) 69.4 (40GB model)
I/O data-transfer rate (Mbytes/sec max)	100 (Ultra DMA mode 5)
Interleave	1:1
Cache buffer	
ST3500641A ST3400633A ST3320633A ST3300622A ST3250624A	16 Mbytes (16,384 kbytes)
ST3500841A ST3400833A ST3320833A ST3300822A ST3250824A ST3200827A ST3160812A ST3120814A	8 Mbytes (8,192 kbytes)
ST3160212A ST3120213A ST3802110A ST3402111A	2 Mbytes (2,048 kbytes)

## 2.5 Physical characteristics

Drive specification	
Maximum height	
(mm) (inches)	26.1 1.028
Maximum width	
(mm) (inches)	101.6 4.000 +/- 0.010
Maximum length	
(mm) (inches)	146.99 5.787
Max weight	
40GB models 250, 200, 160, 120 and 80GB models 300 and 320 GB models 400 and 500GB models	525 grams (1.16 lbs) 580 grams (1.28 lbs) 655 grams (1.44 lbs) 710 grams (1.57 lbs)

#### 2.6 Seek time

Seek measurements are taken with nominal power at 25°C ambient temperature. All times are measured using drive diagnostics. The specifications in the table below are defined as follows:

- Track-to-track seek time is an average of all possible single-track seeks in both directions.
- Average seek time is a true statistical random average of at least 5,000 measurements of seeks between random tracks, less overhead.

*Typical seek times (msec)	Read	Write
Track-to-track	<0.8	<1.0
Average	<11.0	<12.0
Average latency:	4.16	

<sup>\*</sup>Measured in quiet mode

**Note.** These drives are designed to consistently meet the seek times represented in this manual. Physical seeks, regardless of mode (such as track-to-track and average), are expected to meet or exceed the noted values. However, due to the manner in which these drives are formatted, benchmark tests that include command overhead or measure logical seeks may produce results that vary from these specifications.

## 2.7 Start/stop times

	400 and 500GB models	320, 300, 250 and 200GB models	160, 120, 80 and 40GB models
Power-on to Ready (sec)	13 (max)	11 (max)	<10 (max)
Standby to Ready (sec)	13 (max)	11 (max)	<10 (max)
Ready to spindle stop (sec)	14 (max)	12 (max)	<11 (max)

## 2.8 Power specifications

The drive receives DC power (+5V or +12V) through a four-pin standard drive power connector.

#### 2.8.1 Power consumption

Power requirements for the drives are listed in the table on page 25. Typical power measurements are based on an average of drives tested, under nominal conditions, using +5.0V and +12.0V input voltage at 25°C ambient temperature.

#### Spinup power

Spinup power is measured from the time of power-on to the time that the drive spindle reaches operating speed.

#### Seek mode

During seek mode, the read/write actuator arm moves toward a specific position on the disc surface and does not execute a read or write operation. Servo electronics are active. Seek mode power represents the worst-case power consumption, using only random seeks with read or write latency time. This mode is not typical and is provided for worst-case information.

#### • Read/write power and current

Read/write power is measured with the heads on track, based on a 16-sector write followed by a 32-msec delay, then a 16-sector read followed by a 32-msec delay.

#### Operating power and current

Operating power is measured using 40 percent random seeks, 40 percent read/write mode (1 write for each 10 reads) and 20 percent drive idle mode.

#### · Idle mode power

Idle mode power is measured with the drive up to speed, with servo electronics active and with the heads in a random track location.

#### Standby mode

During Standby mode, the drive accepts commands, but the drive is not spinning, and the servo and read/write electronics are in power-down mode.

Table 9: DC power requirements (for 400GB and 500GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.90 (peak)
Idle*	9.30	0.611	0.520
Idle* (with offline activity)	10.40	0.719	0.567
Operating (40% r/w, 40% seek, 20% inop.)	13.00	0.772	0.762
Seeking (random, 20% idle)	12.60	0.613	0.795
Standby	0.80	0.106	0.023
Sleep	0.80	0.106	0.023

Table 10: DC power requirements (for 320 and 300GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.40	0.393	0.453
Idle* (with offline activity)	9.40	0.483	0.582
Operating (40% r/w, 40% seek, 20% inop.)	13.00	0.811	0.746
Seeking (random, 20% idle)	12.80	0.471	0.870
Standby	0.80	0.112	0.02
Sleep	0.80	0.112	0.02

Table 11: DC power requirements (for 250GB and 200GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.20	0.382	0.441
Idle* (with offline activity)	9.10	0.491	0.554
Operating (40% r/w, 40% seek, 20% inop.)	12.80	0.687	0.781
Seeking (random, 20% idle)	12.40	0.446	0.848
Standby	0.80	0.113	0.020
Sleep	0.80	0.110	0.021

Table 12: DC power requirements (for 160GB and 120GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.20	0.590	0.354
Idle* (with offline activity)	9.10	0.880	0.391
Operating (40% r/w, 40% seek, 20% inop.)	12.80	0.920	0.682
Seeking (random, 20% idle)	12.40	0.690	0.745
Standby	0.80	0.113	0.020
Sleep	0.80	0.113	0.020

Table 13: DC power requirements (for 80GB and 40GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.00	0.490	0.379
Idle* (with offline activity)	8.90	0.873	0.378
Operating (40% r/w, 40% seek, 20% inop.)	12.60	0.897	0.676
Seeking (random, 20% idle)	12.20	0.627	0.755
Standby	0.80	0.116	0.018
Sleep	0.80	0.116	0.018

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.8.1.1 Typical current profile

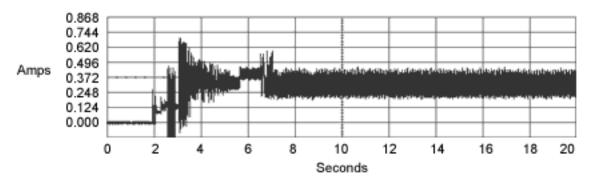


Figure 1 Typical 5V startup and operation current profile

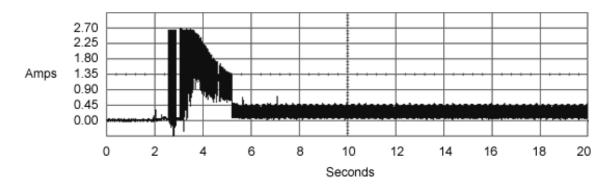


Figure 2 Typical 12V startup and operation current profile

#### 2.8.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 80-ohm resistive load on the +12 volt line or an equivalent 15-ohm resistive load on the +5 volt line.

- Using 12-volt power, the drive is expected to operate with a maximum of 120 mV peak-to-peak square-wave injected noise at up to 10 MHz.
- Using 5-volt power, the drive is expected to operate with a maximum of 100 mV peak-to-peak square-wave injected noise at up to 10 MHz.

**Note.** Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

#### 2.8.3 Voltage tolerance

Voltage tolerance (including noise):

5V ± 5% 12V ± 10%

## 2.8.4 Power-management modes

The drive provides programmable power management to provide greater energy efficiency. In most systems, you can control power management through the system setup program. The drive features the following power-management modes:

Power mode	Heads	Spindle	Buffer
Active	Tracking	Rotating	Enabled
Idle	Tracking	Rotating	Enabled
Standby	Parked	Stopped	Enabled
Sleep	Parked	Stopped	Disabled

#### Active mode

The drive is in Active mode during the read/write and seek operations.

#### Idle mode

The buffer remains enabled, and the drive accepts all commands and returns to Active mode any time disc access is necessary.

#### Standby mode

The drive enters Standby mode when the host sends a Standby Immediate command. If the host has set the standby timer, the drive can also enter Standby mode automatically after the drive has been inactive for a specifiable length of time. The standby timer delay is established using a Standby or Idle command. In Standby mode, the drive buffer is enabled, the heads are parked and the spindle is at rest. The drive accepts all commands and returns to Active mode any time disc access is necessary.

#### Sleep mode

The drive enters Sleep mode after receiving a Sleep command from the host. In Sleep mode, the drive buffer is disabled, the heads are parked and the spindle is at rest. The drive leaves Sleep mode after it receives a Hard Reset or Soft Reset from the host. After receiving a reset, the drive exits Sleep mode and enters Standby mode with all current translation parameters intact.

#### · Idle and Standby timers

Each time the drive performs an Active function (read, write or seek), the standby timer is reinitialized and begins counting down from its specified delay times to zero. If the standby timer reaches zero before any drive

activity is required, the drive makes a transition to Standby mode. In both Idle and Standby mode, the drive accepts all commands and returns to Active mode when disc access is necessary.

## 2.9 Environmental specifications

#### 2.9.1 Ambient temperature

Ambient temperature is defined as the temperature of the environment immediately surrounding the drive. Actual drive case temperature should not exceed 69°C (156°F) within the operating ambient conditions. Recommended measurement locations are shown in See Figure 6 on page 39.

Above 1,000 feet (305 meters), the maximum temperature is derated linearly to 112°F (44°C) at 10,000 feet (3,048 meters).

Operating:	0° to 60°C (32° to 140°F)
Nonoperating:	-40° to 70°C (-40° to 158°F)

## 2.9.2 Temperature gradient

Operating:	20°C per hour (68°F per hour max), without condensation
Nonoperating:	30°C per hour (86°F per hour max)

## 2.9.3 Humidity

## 2.9.3.1 Relative humidity

Operating:	5% to 90% noncondensing (30% per hour max)
Nonoperating:	5% to 95% noncondensing (30% per hour max)

## 2.9.3.2 Wet bulb temperature

Operating:	37.7°C (99.9°F max)
Nonoperating:	40.0°C (104°F max)

## 2.9.4 Altitude

Operating:	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)
Nonoperating:	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)

#### 2.9.5 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

## 2.9.5.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 63 Gs based on half-sine shock pulses of 2 msec. Shocks should not be repeated more than two times per second.

#### 2.9.5.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 300 Gs (500, 400, 320, and 300GB models), 350 Gs (250, 200, 160, 120, 80 and 40GB models) based on a nonrepetitive half-sine shock pulse of 2 msec duration.

#### 2.9.6 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

#### 2.9.6.1 Operating vibration

The following table lists the maximum vibration levels that the drive may experience while meeting the performance standards specified in this document.

5–22 Hz	0.25 Gs (Limited displacement)
23–350 Hz	0.50 Gs
350–500 Hz	0.25 Gs

#### 2.9.6.2 Nonoperating vibration

The following table lists the maximum nonoperating vibration that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation.

5–22 Hz	0.25 Gs (limited displacement)
23-350 Hz	5.0 Gs
350–500 Hz	1.0 Gs

#### 2.10 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels (no pure tones). All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.

**Note.** For seek mode tests, the drive is placed in seek mode only. The number of seeks per second is defined by the following equation:

(Number of seeks per second = 0.4 / (average latency + average access time)

Table 14: Fluid Dynamic Bearing (FDB) motor acoustics

Acoustic mode				
	Idle*	Quiet seek		
ST3402111A	2.0 bels (typ) 2.3 bels (max)	2.4 bels (typ) 2.6 bels (max)		
ST3802110A	2.5 bels (typ) 2.7 bels (max)	2.7 bels (typ) 2.9 bels (max)		
ST3120213A, ST3120814A, ST3160212A, ST3160812A	2.5 bels (typ) 2.7 bels (max)	2.8 bels (typ) 3.0 bels (max)		
ST3200827A, ST3250824A, ST3250624A, ST3320833A, ST3320633A, ST3300622A, ST3300822A	2.7 bels (typ) 2.9 bels (max)	3.0 bels (typ) 3.2 bels (max)		
ST3500641A, ST3500841A, ST3400633A, ST3400833A	2.8 bels (typ) 3.0 bels (max)	3.2 bels (typ) 3.4 bels (max)		

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.11 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

Table 15: Radio frequency environments

Test	Description	Performance level	Reference standard
Electrostatic discharge	Contact, HCP, VCP: ± 4 kV; Air: ± 8 kV	В	EN 61000-4-2: 95
Radiated RF immunity	80 to 1,000 MHz, 3 V/m, 80% AM with 1 kHz sine 900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz	А	EN 61000-4-3: 96 ENV 50204: 95
Electrical fast transient	± 1 kV on AC mains, ± 0.5 kV on external I/O	В	EN 61000-4-4: 95
Surge immunity	± 1 kV differential, ± 2 kV common, AC mains	В	EN 61000-4-5: 95
Conducted RF immunity	150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine	A	EN 61000-4-6: 97
Voltage dips, interrupts	0% open, 5 seconds 0% short, 5 seconds 40%, 0.10 seconds 70%, 0.01 seconds	C C C B	EN 61000-4-11: 94

## 2.12 Reliability

Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read, max.
Annualized Failure Rate (AFR)	0.34% (nominal power, 25°C ambient temperature)
Contact start-stop cycles	50,000 cycles (at nominal voltage and temperature, with 60 cycles per hour and a 50% duty cycle)
Warranty	5 years on distribution units.  To determine the warranty for a specific drive, use a web browser to access the following web page:  www.seagate.com/support/service/  From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.
Preventive maintenance	None required.

## 2.13 Agency certification

### 2.13.1 Safety certification

The drives are recognized in accordance with UL 1950 and CSA C22.2 (950) and meet all applicable sections of IEC950 and EN 60950 as tested by TUV North America.

### 2.13.2 Electromagnetic compatibility

Hard drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (89/336/EEC). Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Seagate uses an independent laboratory to confirm compliance with the EC directives specified in the previous paragraph. Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

#### Korean RRL

If these drives have the Korea Ministry of Information and Communication (MIC) logo, they comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Laboratory (RRL) Ministry of Information and Communication Republic of Korea.

These drives have been tested and comply with the Electromagnetic Interference/Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

- EUT name (model numbers): See table below
- Certificate numbers:

Model	Certificate Number
ST3500841A, ST3500641A, ST3400833A, ST3400633A, ST3320833A, ST3320633A, ST3300822A, ST3300622A, ST3250824A, ST3250624A, ST3200827A, ST3160812A, ST3160212A, ST3120814A, ST3120213A, ST3802110A, ST3402111A	E-H011-05-3453 (B)

Trade name or applicant: Seagate Technology

• Manufacturing date: September 2005

Manufacturer/nationality: Singapore and China

### Australian C-Tick (N176)

If these models have the C-Tick marking, they comply with the Australia/New Zealand Standard AS/NZS3548 1995 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication Authority (ACA).

### 2.13.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate Technology LLC has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disc drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

Radio and television interference. This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, you are encouraged to try one or more of the following corrective measures:

- · Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, you should consult your dealer or an experienced radio/television technician for additional suggestions. You may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

### 2.14 Environmental protection

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

### 2.14.1 European Union Restriction of Hazardous Substances (RoHS)

The European Union Restriction of Hazardous Substances (RoHS) Directive restricts the presence of chemical substances, including Lead (Pb), in electronic products effective July 2006..

A number of parts and materials in Seagate products are procured from external suppliers. We rely on the representations of our suppliers regarding the presence of RoHS substances in these parts and materials. Our supplier contracts require compliance with our chemical substance restrictions, and our suppliers document their compliance with our requirements by providing material content declarations for all parts and materials for the disc drives documented in this publication. Current supplier declarations include disclosure of the inclusion of any RoHS-regulated substance in such parts or materials.

Seagate also has internal systems in place to ensure ongoing compliance with the RoHS Directive and all laws and regulations which restrict chemical content in electronic products. These systems include standard operating procedures that ensure that restricted substances are not utilized in our manufacturing operations, laboratory analytical validation testing, and an internal auditing process to ensure that all standard operating procedures are complied with.

### 2.15 Corrosive environment

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment. Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in Seagate products are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. In addition, electronic components should never be exposed to condensing water on the surface of the printed circuit board assembly (PCBA) or exposed to an ambient relative humidity greater than 95%. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

# 3.0 Configuring and mounting the drive

This section contains the specifications and instructions for configuring and mounting the drive.

## 3.1 Handling and static discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

### Caution:

- Before handling the drive, put on a grounded wrist strap, or ground yourself frequently by touching the metal
  chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the
  entire installation procedure.
- · Handle the drive by its edges or frame only.
- The drive is extremely fragile—handle it with care. Do not press down on the drive top cover.
- Always rest the drive on a padded, antistatic surface until you mount it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.

# 3.2 Breather filter hole precautions

This section contains information regarding the precautions which should be taken regarding the breather filter hole in Seagate hard disc drives. Proper precautions should be taken to ensure full functionality and prevent possible damage to the drive.

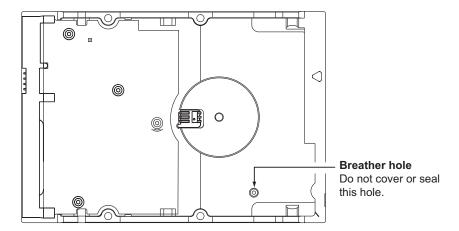


Figure 3 Breather filter hole location

Caution: Do not cover, seal, or insert any object into this hole.

This hole has two purposes:

- To allow condensation inside the hard disc to escape
- To allow air pressure inside the hard disc to equalize with ambient pressure

**Note.** If this hole is covered, sealed, or penetrated by any object, the drive reliability may be compromised and could lead to permanent damage. Covering or sealing this hole voids the warranty.

### 3.3 Jumper settings

### 3.3.1 Master/slave configuration

The options jumper block shown in Figure 4 is used to configure the drive for operation. It is the 8-pin dual header between the interface connector and the power connector. Use the following settings to configure the drive as a master or a slave.

**Master or single drive.** The drive is configured at the factory for a master or single-drive operation with a jumper set on pins 7 and 8.

Drive as slave. Remove all jumpers.

### Drive as master with a non-ATA-compatible slave.

Use this jumper setting only if the drive does not work as a master with no jumpers installed.

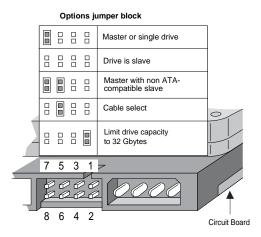


Figure 4 Master/slave jumper settings

### 3.3.2 Cable-select option

Computers that use cable select determine the master and slave drives by selecting or deselecting pin 28, CSEL, on the interface bus. Master and slave drives are determined by their physical position on the cable. To enable cable select, set a jumper on pins 5 and 6 as shown in Figure 4. Refer to your computer manual to determine whether your computer supports this option.

# 3.3.3 Alternate capacity jumper

Some older computers may "hang" at startup if their BIOS detects a disc drive with a capacity greater than 32 Gbytes. This limits the drive's capacity to 32 Gbytes when the alternate capacity jumper is used. To access the full capacity of the drive, you can:

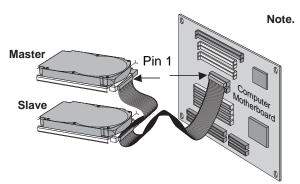
- · Update the BIOS
- Use third-party software such as DiscWizard<sup>™</sup> or Disk Manager
- Use a third-party host adapter

For drives with capacities greater than 32 Gbytes, the alternate capacity jumper changes the total available LBA sectors to 32 Gbytes to solve issues with some BIOS during power on. The ATA Set Features subcommand "F1<sub>H</sub> Report Full Capacity Available" causes Identify Data words 60 and 61 to report the full capacity. See Section 4.1.3 on page 48 for more details on the Set Features command.

Windows XP, Windows Me, Windows 98 or newer versions are needed to support drives with capacities greater than 32 Gbytes.

### 3.3.4 Ultra ATA/100 cable

An 80-conductor 40-pin cable is required to run Ultra DMA mode 3, mode 4, and mode 5. This cable uses even-numbered conductors connected to the ground pins to improve signal integrity.



Note. If you are using a 40-pin, 80-conductor cable, attach the blue connector to the motherboard, the black connector to the master drive, and the gray connector to the slave.

Figure 5 Ultra ATA cable connectors

**Note.** The drive supports both host and drive cable detection. The host detects the 80-conductor cable by sampling pin 34, CBLID—, on the interface bus. The drive detects the 80-conductor cable by sensing a capacitor at the host side through the CBLID— signal. The result is reported in a Fast Rise Detected bit (bit 13 of word 93 in the Identify drive parameter block).

# 3.4 Drive mounting

You can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See Figure 6 for drive mounting dimensions. Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 inches (0.76 mm) around the entire perimeter of the drive for cooling.
- Use only 6-32 UNC mounting screws.
- Do not overtighten the mounting screws (maximum torque: 6 inch-lb.).
- Do not use a drive interface cable that is more than 18 inches long.

#### Notes:

- **1.** Dimensions are shown in inches (mm).
- 2 Dimensions per SFF-8301 specification.

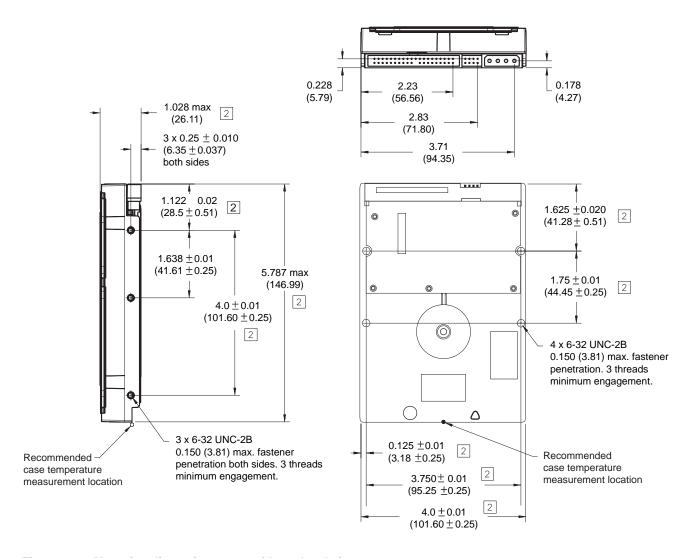


Figure 6 Mounting dimensions—top, side and end view

# 4.0 ATA interface

These drives use the industry-standard ATA task file interface that supports 16-bit data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–5. The drive also supports the use of the IORDY signal to provide reliable high-speed data transfers.

You can use a daisy-chain cable to connect two drives to a single AT host bus. For detailed information about the ATA interface, refer to the draft of AT Attachment with Packet Interface Extension (ATA/ATAPI-7), NCITS T13 1410D, subsequently referred to as the Draft ATA-7 Standard.

## 4.1 ATA interface signals and connector pins

Figure 7 on page 41 summarizes the signals on the ATA interface connector that the drive supports. For a detailed description of these signals, refer to the *Draft ATA-7 Standard*.



Pins 28, 34 and 39 are used for master-slave communication (details shown below).

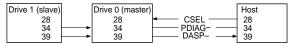


Figure 7 I/O pins and supported ATA signals

# 4.1.1 Supported ATA commands

The following table lists ATA-standard commands that the drive supports. For a detailed description of the ATA commands, refer to the *Draft ATA-7 Standard*. See "S.M.A.R.T. commands" on page 49 for details and subcommands used in the S.M.A.R.T. implementation.

Table 16: Supported ATA commands

Command name	Command code (in hex)
Check Power Mode	98 <sub>H</sub> or E5 <sub>H</sub>
Device Configuration Freeze Lock	B1 <sub>H</sub> / C1 <sub>H</sub>
Device Configuration Identify	B1 <sub>H</sub> / C2 <sub>H</sub>
Device Configuration Restore	B1 <sub>H</sub> / C0 <sub>H</sub>
Device Configuration Set	B1 <sub>H</sub> / C3 <sub>H</sub>
Device Reset	08 <sub>H</sub>
Download Microcode	92 <sub>H</sub>
Execute Device Diagnostics	90 <sub>H</sub>
Flush Cache	E7 <sub>H</sub>
Flush Cache Extended	EA <sub>H</sub>
Format Track	50 <sub>H</sub>
Identify Device	EC <sub>H</sub>
Idle	97 <sub>H</sub> or E3 <sub>H</sub>
Idle Immediate	95 <sub>H</sub> or E1 <sub>H</sub>
Initialize Device Parameters	91 <sub>H</sub>
Read Buffer	E4 <sub>H</sub>
Read DMA	C8 <sub>H</sub>
Read DMA Extended	25 <sub>H</sub>
Read DMA Without Retries	C9 <sub>H</sub>
Read Log Ext	2F <sub>H</sub>
Read Multiple	C4 <sub>H</sub>
Read Multiple Extended	29 <sub>H</sub>
Read Native Max Address	F8 <sub>H</sub>
Read Native Max Address Extended	27 <sub>H</sub>
Read Sectors	20 <sub>H</sub>
Read Sectors Extended	24 <sub>H</sub>
Read Sectors Without Retries	21 <sub>H</sub>
Read Verify Sectors	40 <sub>H</sub>
Read Verify Sectors Extended	42 <sub>H</sub>
Read Verify Sectors Without Retries	41 <sub>H</sub>
Recalibrate	10 <sub>H</sub>
Security Disable Password	F6 <sub>H</sub>
Security Erase Prepare	F3 <sub>H</sub>

Command name	Command code (in hex)
Security Erase Unit	F4 <sub>H</sub>
Security Freeze	F5 <sub>H</sub>
Security Set Password	F1 <sub>H</sub>
Security Unlock	F2 <sub>H</sub>
Seek	70 <sub>H</sub>
Set Features	EF <sub>H</sub>
Set Max Address	F9 <sub>H</sub>
Note: Individual Set Max Address commands are identified by the value placed in the Set Max Features register as defined to the right.	Address: 00 <sub>H</sub> Password: 01 <sub>H</sub> Lock: 02 <sub>H</sub> Unlock: 03 <sub>H</sub> Freeze Lock: 04 <sub>H</sub>
Set Max Address Extended	37 <sub>H</sub>
Set Multiple Mode	C6 <sub>H</sub>
Sleep	99 <sub>H</sub> or E6 <sub>H</sub>
S.M.A.R.T. Disable Operations	B0 <sub>H</sub> / D9 <sub>H</sub>
S.M.A.R.T. Enable/Disable Autosave	B0 <sub>H</sub> / D2 <sub>H</sub>
S.M.A.R.T. Enable Operations	B0 <sub>H</sub> / D8 <sub>H</sub>
S.M.A.R.T. Execute Offline	B0 <sub>H</sub> / D4 <sub>H</sub>
S.M.A.R.T. Read Attribute Thresholds	B0 <sub>H</sub> / D1 <sub>H</sub>
S.M.A.R.T. Read Data	B0 <sub>H</sub> / D0 <sub>H</sub>
S.M.A.R.T. Read Log Sector	B0 <sub>H</sub> / D5 <sub>H</sub>
S.M.A.R.T. Return Status	B0 <sub>H</sub> / DA <sub>H</sub>
S.M.A.R.T. Save Attribute Values	B0 <sub>H</sub> / D3 <sub>H</sub>
S.M.A.R.T. Write Log Sector	B0 <sub>H</sub> / D6 <sub>H</sub>
Standby	96 <sub>H</sub> or E2 <sub>H</sub>
Standby Immediate	94 <sub>H</sub> or E0 <sub>H</sub>
Write Buffer	E8 <sub>H</sub>
Write DMA	CA <sub>H</sub>
Write DMA Extended	35 <sub>H</sub>
Write DMA Without Retries	CB <sub>H</sub>
Write Log Extended	3F <sub>H</sub>
Write Multiple	C5 <sub>H</sub>
Write Multiple Extended	39 <sub>H</sub>
Write Sectors	30 <sub>H</sub>
Write Sectors Without Retries	31 <sub>H</sub>
Write Sectors Extended	34 <sub>H</sub>

# 4.1.2 Identify Device command

The Identify Device command (command code  $EC_H$ ) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in the Table 16 on page 42. All reserved bits or words should be set to zero. Parameters listed with an "x" are drive-specific or vary with the state of the drive. See Section 2.0 on page 3 for default parameter settings.

The following commands contain drive-specific features that may not be included in the *Draft ATA-7 Standard*.

Word	Description	Value
0	Configuration information:  • Bit 15: 0 = ATA; 1 = ATAPI  • Bit 7: removable media  • Bit 6: removable controller  • Bit 0: reserved	0C5A <sub>H</sub>
1	Number of logical cylinders	16,383
2	ATA-reserved	0000 <sub>H</sub>
3	Number of logical heads	16
4	Retired	0000 <sub>H</sub>
5	Retired	0000 <sub>H</sub>
6	Number of logical sectors per logical track: 63	003F <sub>H</sub>
7–9	Retired	0000 <sub>H</sub>
10–19	Serial number: (20 ASCII characters, 0000 <sub>H</sub> = none)	ASCII
20	Retired	0000 <sub>H</sub>
21	Retired	0400 <sub>H</sub>
22	Obsolete	0000 <sub>H</sub>
23–26	Firmware revision (8 ASCII character string, padded with blanks to end of string)	x.xx
27–46	Drive model number (40 ASCII characters, padded with blanks to end of string)	ST3xxxxA
47	(Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)	8010 <sub>H</sub>
48	Reserved	0000 <sub>H</sub>
49	Standard Standby timer, IORDY supported and may be disabled	2F00 <sub>H</sub>
50	ATA-reserved	0000 <sub>H</sub>
51	PIO data-transfer cycle timing mode	0200 <sub>H</sub>
52	Retired	0200 <sub>H</sub>
53	Words 54–58, 64–70 and 88 are valid	0007 <sub>H</sub>
54	Number of current logical cylinders	xxxx <sub>H</sub>
55	Number of current logical heads	xxxx <sub>H</sub>
56	Number of current logical sectors per logical track	xxxx <sub>H</sub>
57–58	Current capacity in sectors	xxxx <sub>H</sub>
59	Number of sectors transferred during a Read Multiple or Write Multiple command	xxxx <sub>H</sub>

Word	Description	Value
60–61	Total number of user-addressable LBA sectors available (see Section 2.2 for related information)  *Note: The maximum value allowed in this field is: 0FFFFFFFh (268,435,455 sectors, 137 Gbytes). Drives with capacities over 137 Gbytes will have 0FFFFFFFh in this field and the actual number of user-addressable LBAs specified in words 100-103. This is required for drives that support the 48-bit addressing feature.	ST3402111A = 78,165,360 ST3802110A = 156,301,488 ST3120213A = 0FFFFFFFh* ST3120814A = 0FFFFFFFh* ST3160212A = 0FFFFFFFh* ST3160812A = 0FFFFFFFh* ST3200827A = 0FFFFFFFh* ST3250624A = 0FFFFFFFh* ST3250824A = 0FFFFFFFh* ST3300622A = 0FFFFFFFh* ST3300822A = 0FFFFFFFh* ST3320633A = 0FFFFFFFh* ST3400633A = 0FFFFFFFh* ST3400833A = 0FFFFFFFh* ST3500641A = 0FFFFFFFh* ST3500841A = 0FFFFFFFh*
62	Retired	0000 <sub>H</sub>
63	Multiword DMA active and modes supported (see note following this table)	xx07 <sub>H</sub>
64	Advanced PIO modes supported (modes 3 and 4 supported)	0003 <sub>H</sub>
65	Minimum multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
66	Recommended multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
67	Minimum PIO cycle time without IORDY flow control (240 nsec)	00F0 <sub>H</sub>
68	Minimum PIO cycle time with IORDY flow control (120 nsec)	0078 <sub>H</sub>
69–74	ATA-reserved	0000 <sub>H</sub>
75	Queue depth	0000 <sub>H</sub>
76–79	SATA-specific	xxxx <sub>H</sub>
80	Major version number	007E <sub>H</sub>
81	Minor version number	0000 <sub>H</sub>
82	Command sets supported	346B <sub>H</sub>
83	Command sets supported	7D01 <sub>H</sub>
84	Command sets support extension	4003 <sub>H</sub>
85	Command sets enabled	34xx <sub>H</sub>
86	Command sets enabled	3xxx <sub>H</sub>
87	Command sets enable extension	4003 <sub>H</sub>
88	Ultra DMA support and current mode (see note following this table)	xx3F <sub>H</sub>
89	Security erase time	0000 <sub>H</sub>
90	Enhanced security erase time	0000 <sub>H</sub>
92	Master password revision code	FFFE <sub>H</sub>
93	Hardware reset value (see description following this table)	xxxx <sub>H</sub>
95–99	ATA-reserved	0000 <sub>H</sub>

Word	Description	Value
100–103	Total number of user-addressable LBA sectors available (see Section 2.2 for related information). These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFFh.	ST3402111A = 78,165,360 ST3802110A = 156,301,488 ST3120213A = 234,441,648 ST3120814A = 234,441,648 ST3160212A = 312,581,808 ST3160812A = 312,581,808 ST3200827A = 390,721,968 ST3250624A = 488,397,168 ST3250824A = 488,397,168 ST3300622A = 586,072,368 ST3300822A = 586,072,368 ST3320633A = 625,142,448 ST3320633A = 625,142,448 ST3400633A = 781,422,768 ST3400833A = 781,422,768 ST3500641A = 976,773,168 ST3500841A = 976,773,168
104–127	ATA-reserved	0000 <sub>H</sub>
128	Security status	0001 <sub>H</sub>
129–159	Seagate-reserved	xxxx <sub>H</sub>
160–254	ATA-reserved	0000 <sub>H</sub>
255	Integrity word	xxA5 <sub>H</sub>

Note. Advanced Power Management (APM) and Automatic Acoustic Management (AAM) features are not supported

**Note.** See the bit descriptions below for words 63, 88, and 93 of the Identify Drive data:

Description (if bit is set to 1)			
Bit	Word 63		
0	Multiword DMA mode 0 is supported.		
1	Multiword DMA mode 1 is supported.		
2	Multiword DMA mode 2 is supported.		
8	Multiword DMA mode 0 is currently active.		
9	Multiword DMA mode 1 is currently active.		
10	Multiword DMA mode 2 is currently active.		
Bit	Word 88		
0	Ultra DMA mode 0 is supported.		
1	Ultra DMA mode 1 is supported.		
2	Ultra DMA mode 2 is supported.		
3	Ultra DMA mode 3 is supported.		
4	Ultra DMA mode 4 is supported.		
5	Ultra DMA mode 5 is supported.		
8	Ultra DMA mode 0 is currently active.		
9	Ultra DMA mode 1 is currently active.		
10	Ultra DMA mode 2 is currently active.		
11	Ultra DMA mode 3 is currently active.		

12	Ultra DMA mode 4 is currently active.
13	Ultra DMA mode 5 is currently active.
Bit	Word 93

## 4.1.3 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows:

02 <sub>H</sub>	Enable write cache (default).						
03 <sub>H</sub>	Set transfer mode (based on value in Sector Count register).						
	Sector Count register values:						
	00 <sub>H</sub>	00 <sub>H</sub> Set PIO mode to default (PIO mode 2).					
	01 <sub>H</sub>	Set PIO mode to default and disable IORDY (PIO mode 2).					
	08 <sub>H</sub> PIO mode 0						
	09 <sub>H</sub> PIO mode 1						
	0A <sub>H</sub>	PIO mode 2					
	0B <sub>H</sub> PIO mode 3						
	0C <sub>H</sub> PIO mode 4 (default)						
	20 <sub>H</sub> Multiword DMA mode 0						
	21 <sub>H</sub> Multiword DMA mode 1						
	22 <sub>H</sub> Multiword DMA mode 2						
	40 <sub>H</sub> Ultra DMA mode 0						
	41 <sub>H</sub>	Ultra DMA mode 1					
	42 <sub>H</sub>	Ultra DMA mode 2					
	43 <sub>H</sub>	Ultra DMA mode 3					
	44 <sub>H</sub>	Ultra DMA mode 4					
	45 <sub>H</sub>	Ultra DMA mode 5					
55 <sub>H</sub>	Disable read look-ahead (read cache) feature.						
82 <sub>H</sub>	Disable write cache.						
$AA_H$	Enable read look-ahead (read cache) feature (default).						
F1 <sub>H</sub>	Report full capacity available						

**Note.** At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

### 4.1.4 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for disc drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attributes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-7 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4<sub>H</sub>) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <a href="http://seatools.seagate.com">http://seatools.seagate.com</a>.

This drive is shipped with S.M.A.R.T. features disabled. You must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

Code in features register	S.M.A.R.T. command
D0 <sub>H</sub>	S.M.A.R.T. Read Data
D2 <sub>H</sub>	S.M.A.R.T. Enable/Disable Attribute Autosave
D3 <sub>H</sub>	S.M.A.R.T. Save Attribute Values
D4 <sub>H</sub>	S.M.A.R.T. Execute Off-line Immediate (runs DST)
D5 <sub>H</sub>	S.M.A.R.T. Read Log Sector
D6 <sub>H</sub>	S.M.A.R.T. Write Log Sector
D8 <sub>H</sub>	S.M.A.R.T. Enable Operations
D9 <sub>H</sub>	S.M.A.R.T. Disable Operations
DA <sub>H</sub>	S.M.A.R.T. Return Status

**Note.** If an appropriate code is not written to the Features Register, the command is aborted and 0x04 (abort) is written to the Error register.

# 5.0 Seagate Technology support services

### Internet

For information regarding Seagate products and services, visit <u>www.seagate.com</u>. Worldwide support is available 24 hours daily by email for your questions.

### **Presales Support:**

Presales@Seagate.com

### **Technical Support:**

DiscSupport@Seagate.com

### **Warranty Support:**

http://www.seagate.com/support/service/index.html

### mySeagate

my.seagate.com is the industry's first Web portal designed specifically for OEMs and distributors. It provides self-service access to critical applications, personalized content and the tools that allow our partners to manage their Seagate account functions. Submit pricing requests, orders and returns through a single, password-protected Web interface-anytime, anywhere in the world.

# spp.seagate.com

spp.seagate.com supports Seagate resellers with product information, program benefits and sales tools. You may register for customized communications that are not available on the web. These communications contain product launch, EOL, pricing, promotions and other channel-related information. To learn more about the benefits or to register, go to spp.seagate.com, any time, from anywhere in the world.

## **Seagate Service Centers**

### **Presales Support**

Our Presales Support staff can help you determine which Seagate products are best suited for your specific application or computer system, as well as product availability and compatibility.

### **Technical Support**

Seagate technical support is available to assist you online at <u>support.seagate.com</u> or through one of our call centers. Have your system configuration information and your "ST" model number available.

**SeaTDD™** (+1-405-324-3655) is a telecommunications device for the deaf (TDD). You can send questions or comments 24 hours daily and exchange messages with a technical support specialist during normal business hours for the call center in your region.

## **Customer Service Operations**

### **Warranty Service**

Seagate offers worldwide customer support for Seagate products. Seagate distributors, OEMs and other direct customers should contact their Seagate Customer Service Operations (CSO) representative for warranty-related issues. Resellers or end users of drive products should contact their place of purchase or Seagate warranty service for assistance. Have your serial number and model or part number available.

### **Data Recovery Services**

Seagate offers data recovery services for all formats and all brands of storage media. Our data recovery services labs are currently located throughout the world. Additional information, including an online request form and data loss prevention resources, is available at <a href="http://services.seagate.com/index.aspx">http://services.seagate.com/index.aspx</a>

### **Authorized Service Centers**

Seagate Service Centers are available on a global basis for the return of defective products. Contact your customer support representative for the location nearest you.

## **USA/Canada/Latin America support services**

For an extensive list of telephone numbers to technical support, presales and warranty service in USA/ Canada/Latin America, including business hours, go to the "Contact Us" page on <a href="https://www.seagate.com">www.seagate.com</a>.

## **Global Customer Support**

Presales, Technical, and Warranty Support

Call Center Toll-free Direct dial

USA, Canada,

and Mexico 1-800-SEAGATE +1-405-324-4700

**Data Recovery Services** 

Call Center Toll-free Direct dial FAX

USA, Canada, 1-800-475-01435 +1-905-474-2162 1-800-475-0158 and Mexico +1-905-474-2459

## **Europe, the Middle East and Africa Support Services**

For an extensive list of telephone numbers to technical support, presales and warranty service in Europe, the Middle East and Africa, go to the "Contact Us" page on <a href="https://www.seagate.com">www.seagate.com</a>.

## **Asia/Pacific Support Services**

For an extensive list of telephone numbers to technical support, presales and warranty service in Asia/Pacific, go to the "Contact Us" page on <a href="https://www.seagate.com">www.seagate.com</a>.

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